

**10 September 2024**

# **Langbotics - Let robotics agent reason about the world**

**Simone Voto | Concept Reply**

# ABOUT ME



## Simone Voto

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on defining and realizing innovative projects using  
robots



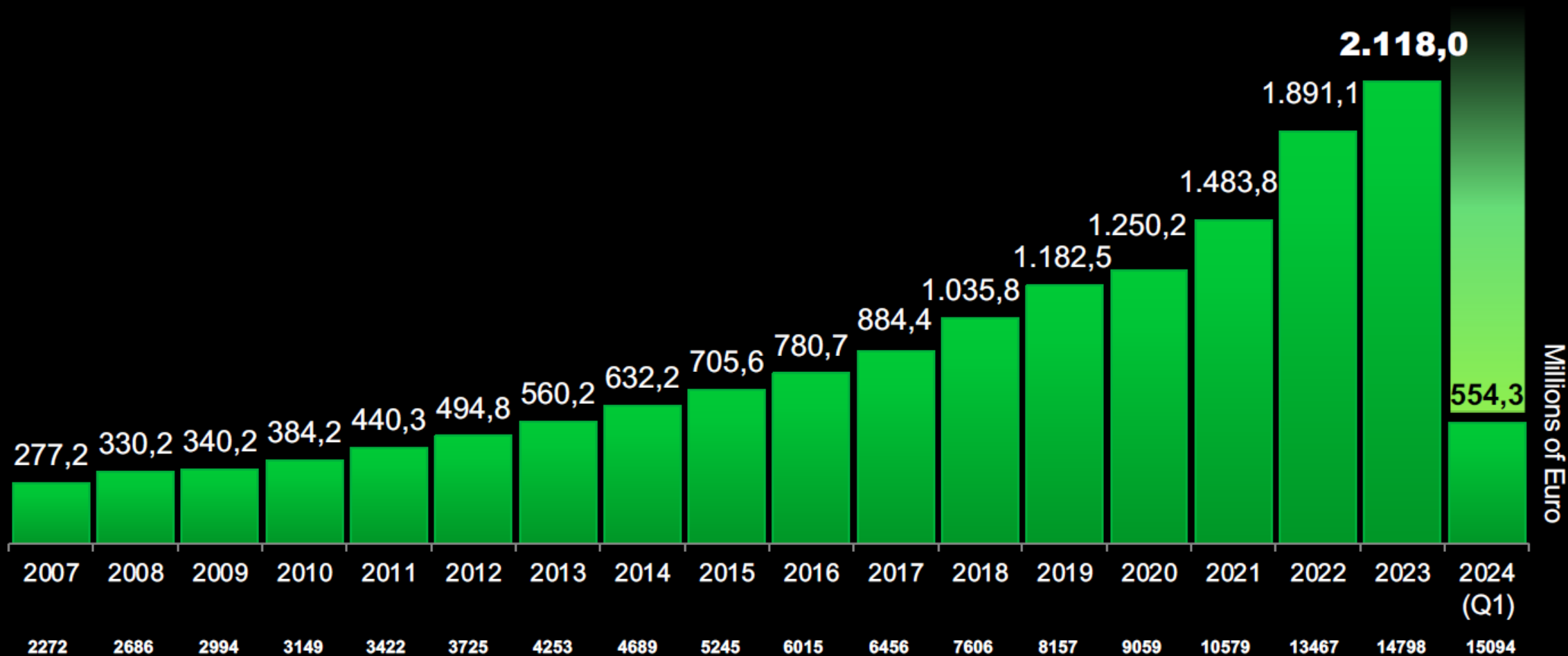
# ABOUT US

# **REPLY CORPORATE INTRODUCTION**



**To excel in helping our customers exploit relevant innovation brought about by economic changes and driven by internet technologies.**

# REVENUE & PEOPLE



# WHERE WE ARE



# REPLY SERVICES

## PEOPLE

DIGITAL HUMANS

COPILOTS

WORKPLACES

## MACHINES

ROBOTICS

AUTONOMOUS  
THINGS

IOT & CONNECTED  
PRODUCTS

## DIGITAL EXPERIENCE

PRODUCT DESIGN  
BRAND EXPERIENCE

DIGITAL MARKETING

IMMERSIVE  
EXPERIENCES

## ENTERPRISE PLATFORMS

ADVANCED  
ANALYTICS

INDUSTRY SPECIFIC  
PLATFORMS

APPLICATION SUITES  
& CX PLATFORMS

## AI

## FOUNDATIONS

COMPUTING PLATFORMS

DATA PLATFORMS

WEB 3.0

CYBERSECURITY

NETWORK

3D & SPATIAL COMPUTING



# CONCEPT REPLY



# ABOUT US



## Concept Reply

We specialise in end-to-end Internet of Things solutions across various domains, including industrial applications, connected and autonomous vehicles, and connected products.

We support our customers in making their products, services, cities, and processes smarter and more automated to unlock new business models.

Our team is skilled in Hardware design, embedded software, cloud solutions, robotics, innovative human-machine interfaces, ML & AI, quality, and project management.



# Agenda

1. Introduction to Human-Robot interaction
2. Problem of the classical Human-Robot interaction
3. Langbotics: natural language Reply solution

# Human-Robot Interaction

# HUMAN-ROBOT INTERACTION

## OVERVIEW

Human-Robot Interaction (HRI) is the study of how humans and robots interact and communicate in shared environments. It focuses on:

- **Understanding:** How robots can interpret human language, gestures, and emotions.
- **Collaboration:** Designing robots to work seamlessly alongside humans in various settings, such as factories, homes, and hospitals.
- **Autonomy vs. Control:** Finding the right balance between robot independence and human oversight to ensure safety and efficiency.
- **User Experience (UX):** Developing intuitive interfaces and interactions that make robots easy and effective to use.

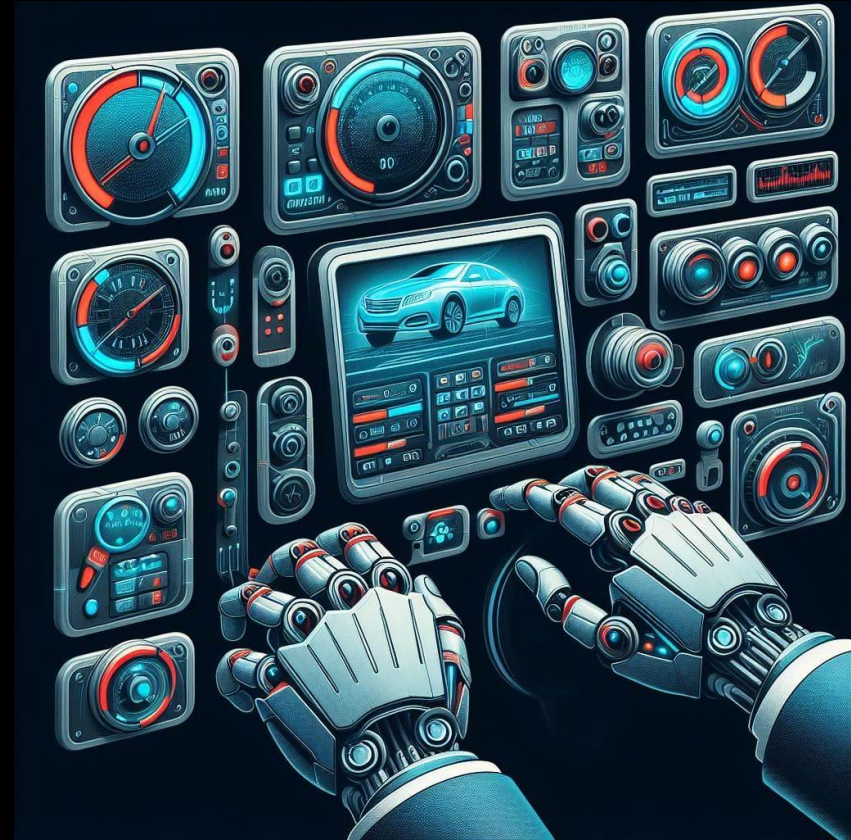


# HUMAN-ROBOT INTERACTION

## Classical human-robot interaction

### Dashboards and buttons

- They require operators to have detailed knowledge and memory of functions
- They are inconvenient and demand a high level of experience
- They limit communication expressiveness and variety
- They reduce human-robot interaction effectiveness



# HUMAN-ROBOT INTERACTION

## Challenges of static Robotic Actions

### Predefined actions

- They limit robot adaptability and flexibility
- They are problematic in variable environments
- They reduce robot versatility and increase training costs
- They hinder robot performance in complex tasks



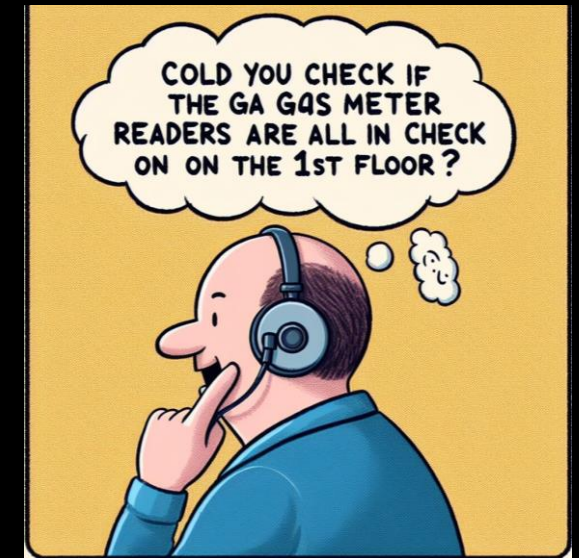
# **Human-Robot interaction in natural language**

# SOLUTION

## Human-robot interaction in natural language

### The advantages include:

- **Intuitive Communication:** No specialized training needed
- **Flexibility and Adaptability:** Robots can handle a wide array of inputs combining their low-level skillset
- **Personal Experience:** Robots understand context and sentiment.
- **Transformative Impact:** Robots are more accessible and personable.



spelling errors courtesy of DALL-E 3



# SOLUTION

## LANGBOTICS

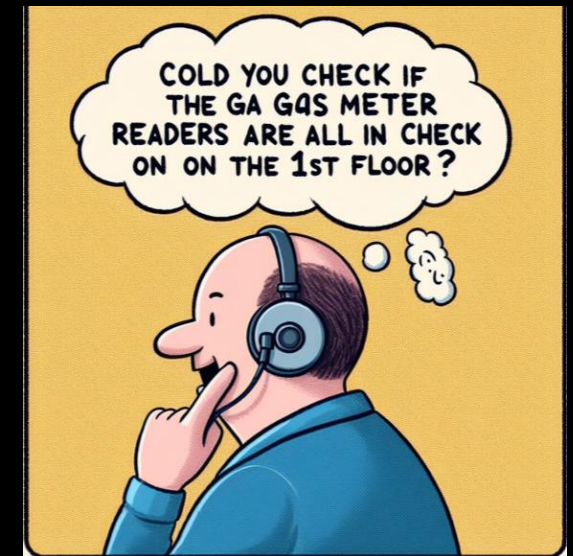
- **NATURAL LANGUAGE INTERACTION:** the user expresses their need or the task to be performed in natural language, as if they were talking to a person.
- **COMMAND DECODING:** langbotics uses state-of-the-art large language models to understand the meaning of the command and its implications.
- **ROBOT SELECTION:** the system identifies the robots with the skills necessary to complete the task.
- **PLANNING AND ASSIGNMENT:** langbotics generates a specific mission for each robot involved, defining the actions to be taken and their sequence.
- **TASK EXECUTION:** the robots collaborate to complete the task autonomously and safely.



# SOLUTION

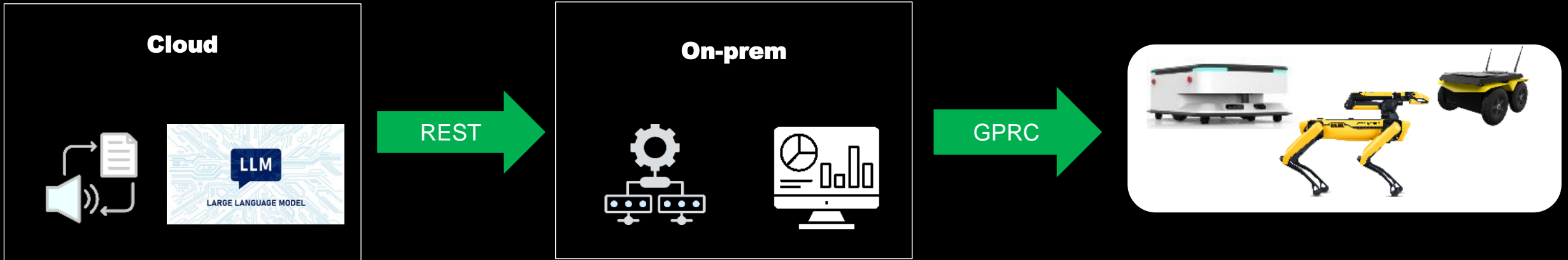
## Natural language Mission decoding

- navigation, 1° floor
- localization, all 1° floor rooms
- for each room:
  - navigation, room
  - search, meter reader
  - meter reader verification



spelling errors courtesy of DALL-E 3

# SOLUTION ARCHITECTURE





# CONTACT US

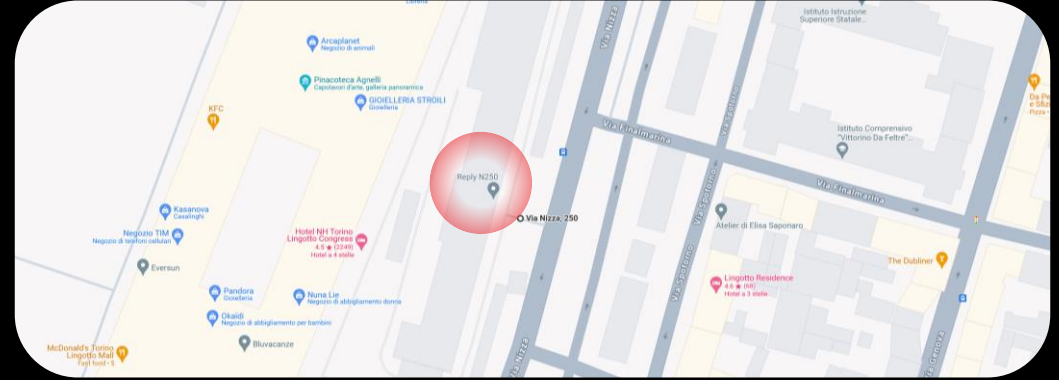
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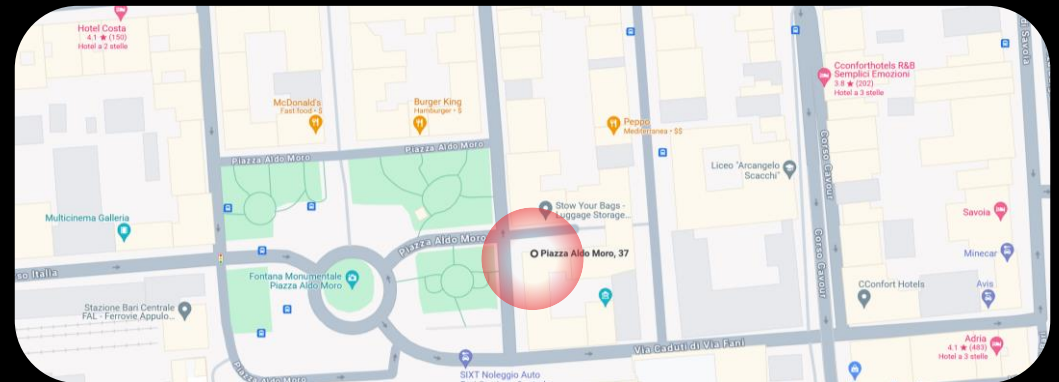
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## Social Link

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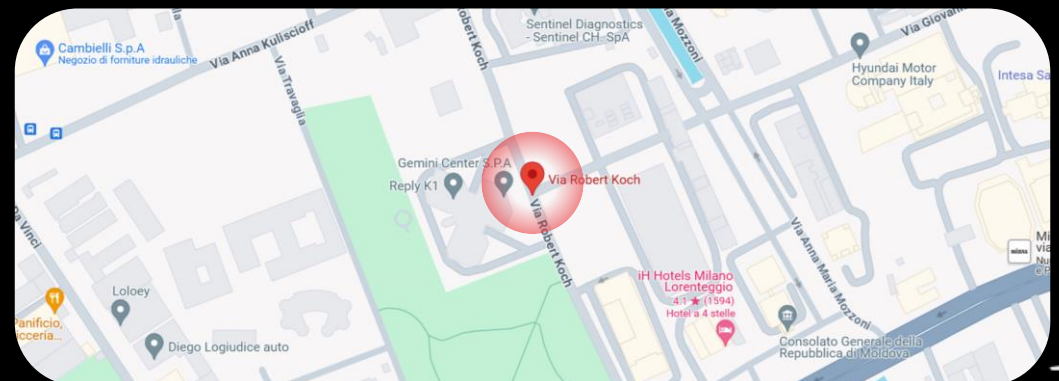
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**THANK YOU**