

**IEEE  
RTSI  
2024**

RESEARCH AND  
TECHNOLOGIES  
FOR SOCIETY  
AND INDUSTRY  

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8<sup>th</sup> International Forum

POLITECNICO DI MILANO  
Polo Territoriale di Lecco  
SEPTEMBER 18-20, 2024

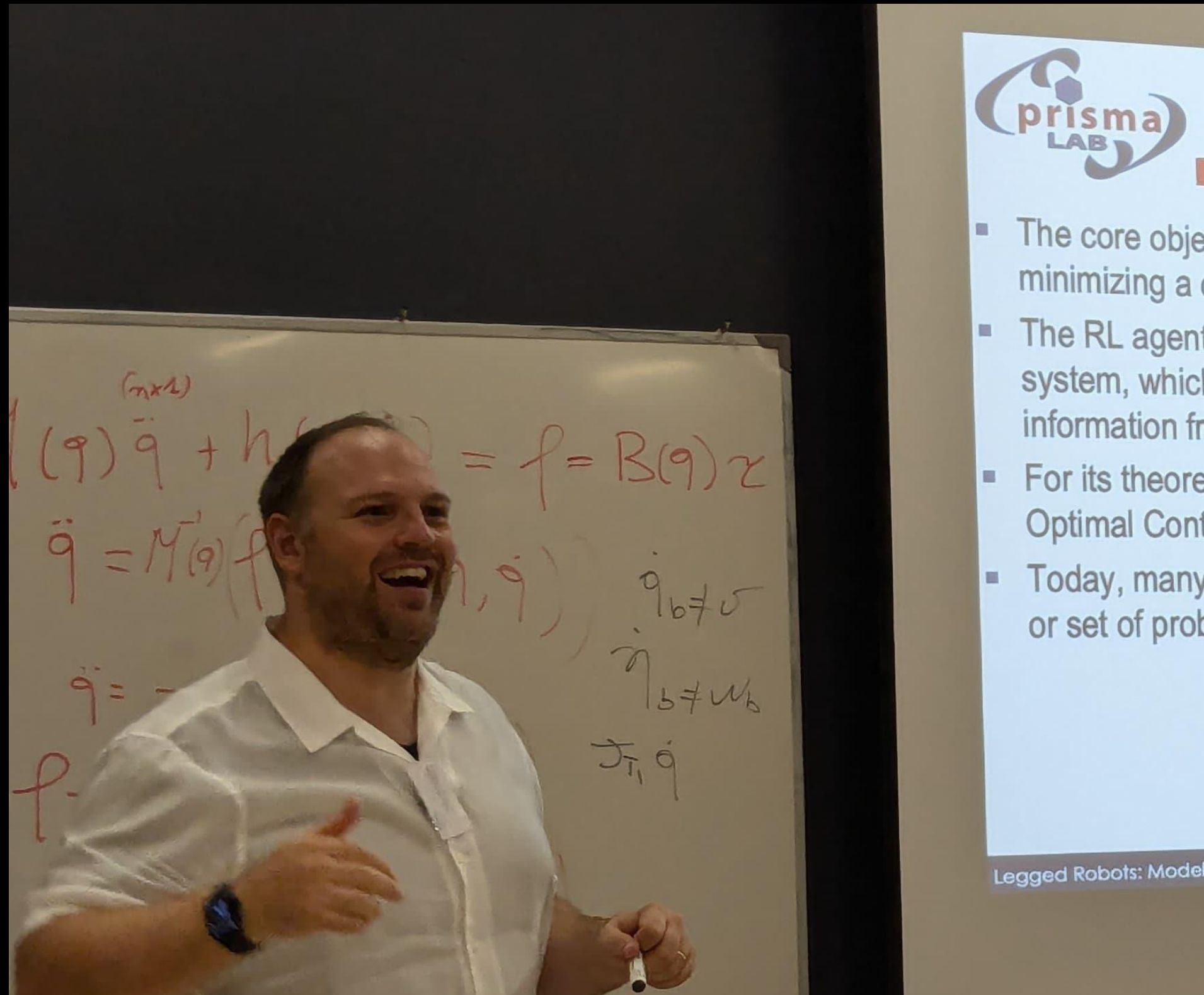
# **Humanoid Robots: Challenges and Perspectives in Automation**

**Fabio Ruggiero**

*Department of Electrical Engineering and Information Technology*

*University of Naples Federico II*

# Bio-sketch



- ✓ Ph.D. degree in electrical engineering and information technology from the University of Naples Federico II, Naples, Italy, in 2010
- ✓ Visiting Ph.D. Student with Northwestern University from September 2009 to March 2010
- ✓ Associate Professor at the Department of Electrical Engineering and Information Technology, University of Naples Federico II, Naples, Italy
- ✓ Research interests include aerial robotics, dynamic nonprehensile manipulation, and legged systems
- ✓ Participated in several European research projects, also as leader of work packages, and principal investigator of three projects funded by the Italian Ministry of Research
- ✓ Chair of the IEEE Italy RAS Chapter
- ✓ Associate Editor for the IEEE Transactions on Robotics.

 [fabio.ruggiero@unina.it](mailto:fabio.ruggiero@unina.it)

 <http://www.fabioruggiero.name>

# The PRISMA Team



- ✓ *3 full professors, 3 associate professors, 4 assistant professors*
- ✓ *13 research assistants, 14 PhD students, 7 support staff*
- ✓ *1.4 M€ financial support a year (from competitive research projects)*
- ✓ *>35 years of research activity*
- ✓ *Collaboration with >150 foreign institutions & companies*

# Our Research Agenda



- ✓ *Aerial Robotics*
- ✓ *AI & Cognitive Robotics*
- ✓ *Dynamic and Legged Robotics*

- ✓ *Human–Robot Interaction*
- ✓ *Industrial Robotics*
- ✓ *Medical Robotics*

# Our EU Research Projects

RODyNAM  
HENDO THERANOSTICS  
DEXMART  
INVERSE  
REFILLS  
Harmony  
SAPHARI  
PHRIENDS

Manipulation & Interaction



AIRobots  
AEROARMS  
AERIAL-CORE  
SHERPA  
ARAS  
HYFLIERS  
AERO-TRAIN

Aerial Robotics

European ROBOTICS Research Network  
EUROON  
ROCK EU  
ROCK eu<sup>2</sup>  
eu Robotics  
ethicbots  
ECHORD  
European Robotics Challenges  
euROBIN  
RIMA  
DIH<sup>2</sup>

Networking & Technology Transfer

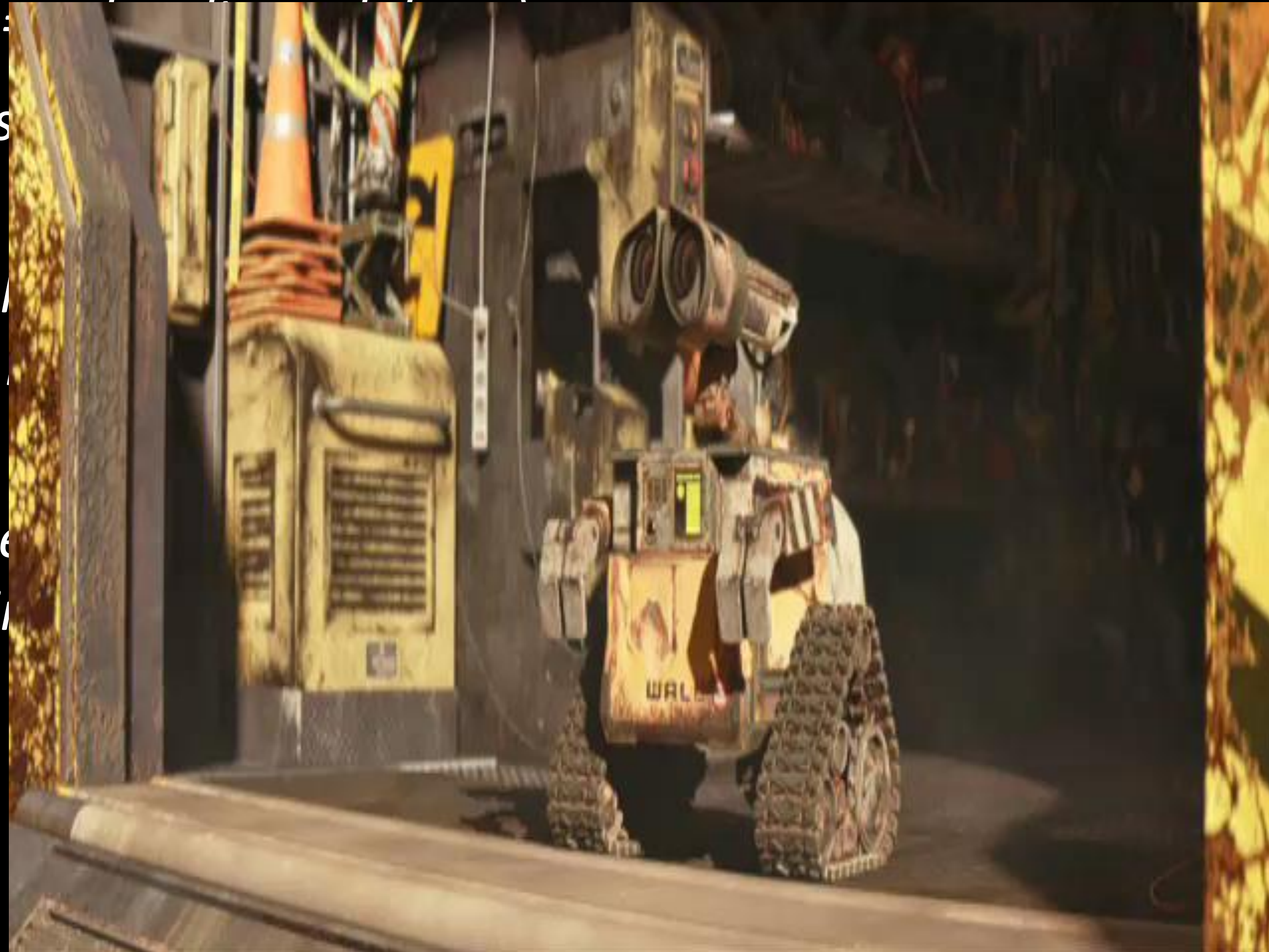
# What is a Robot?

Robot (*robotica*)

One of humans  
(*mythology*)

Common people  
walk, see, and  
(*fiction*)

The robot is seen  
execute tasks in



artifacts

can speak,  
humans (*science*

is able to  
labour (*reality*)

# Why Humanoid Robots?

- ✓ *Human are humanity's favorite subject*
- ✓ *Human example*
- ✓ *Understanding intelligence*
- ✓ *Anthropic environments*
- ✓ *Human interaction*
- ✓ *Entertainment, culture, and surrogates*

# History of Robotics

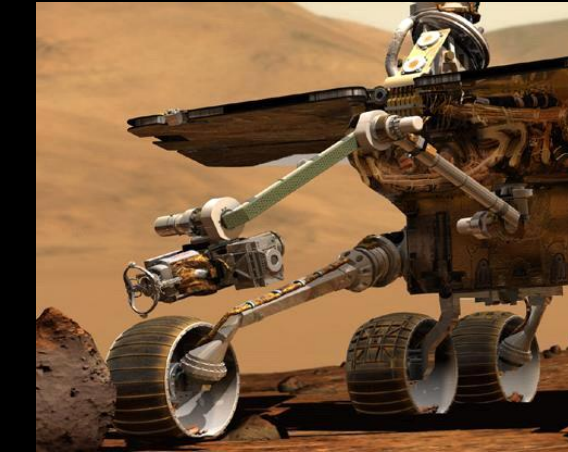
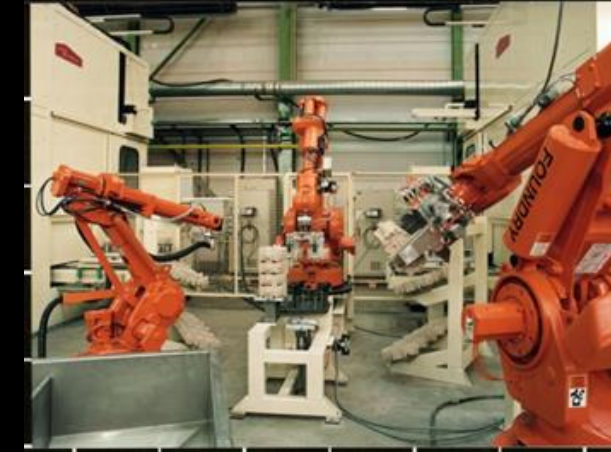
Humans' DREAM of replicating themselves

NEED for useful machines

industrial robotics

1960-1980

manufacturing applications



field robotics

1980-2000

space applications



service robotics

2000-2020

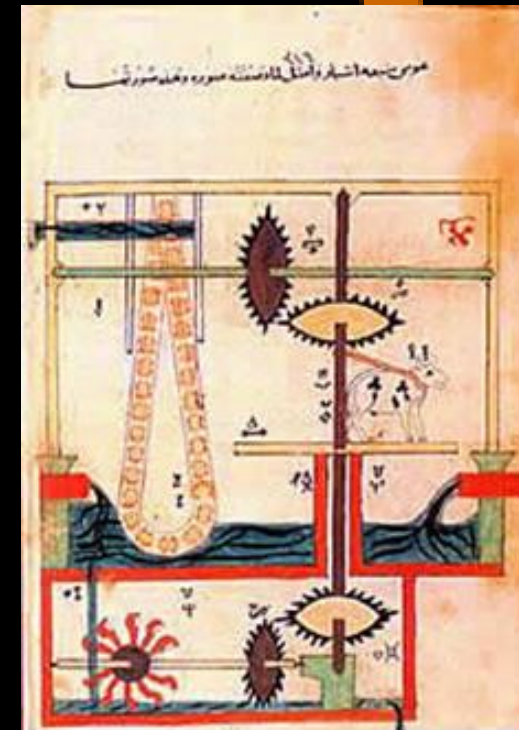
medical applications

2020-2040

personal robotics

humanoid robotics

?



1200



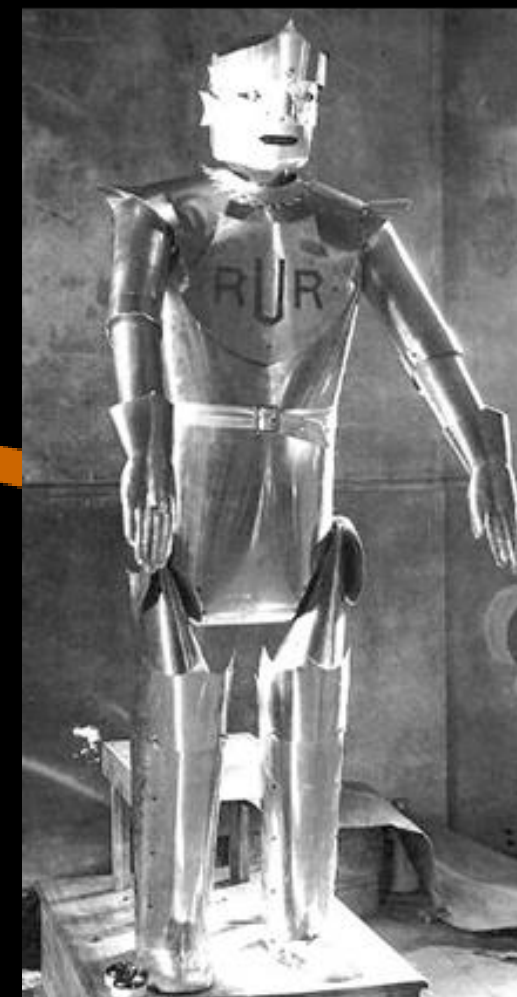
1500



1550



1750



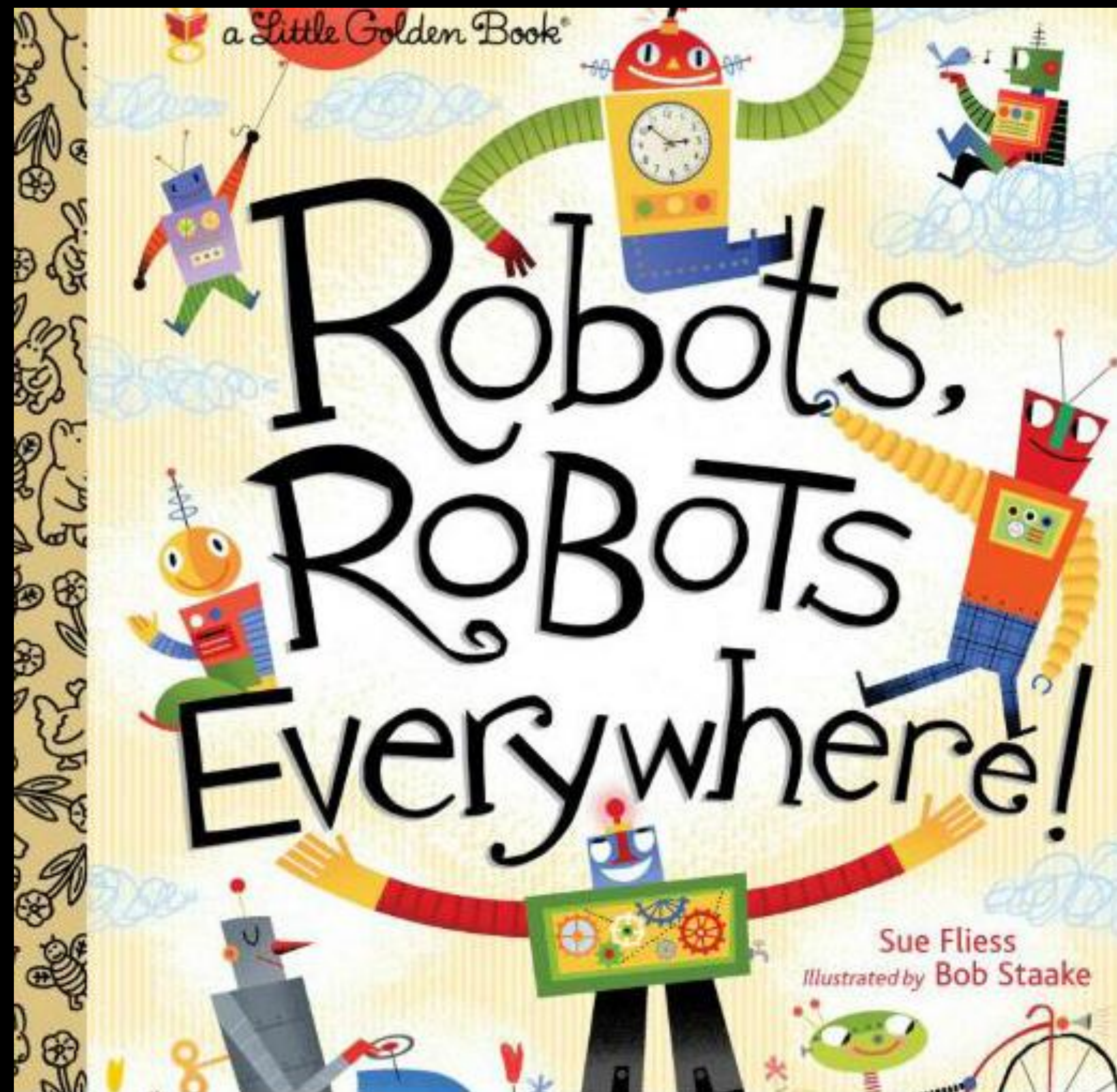
1920



2005

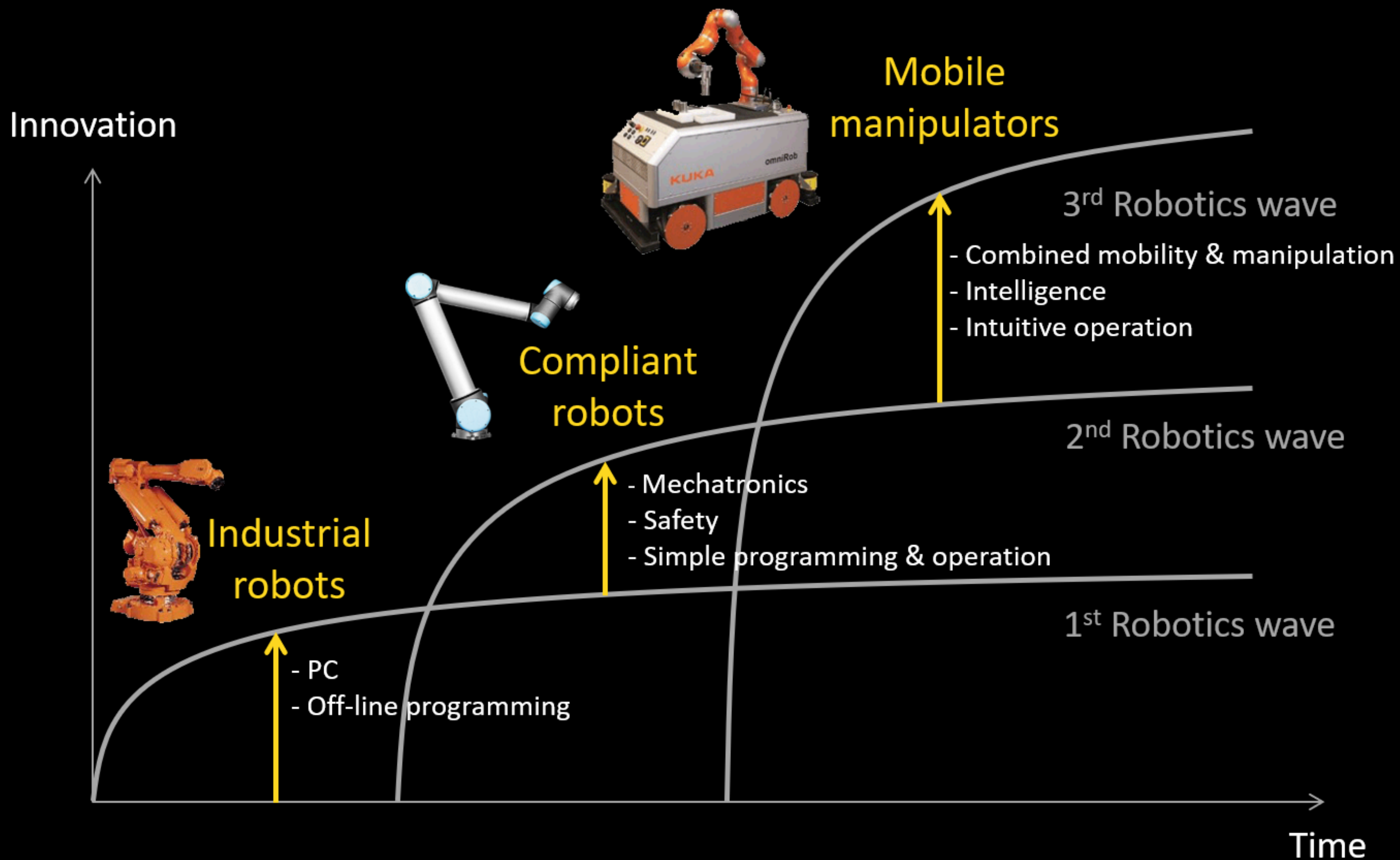


# The Age of Robots



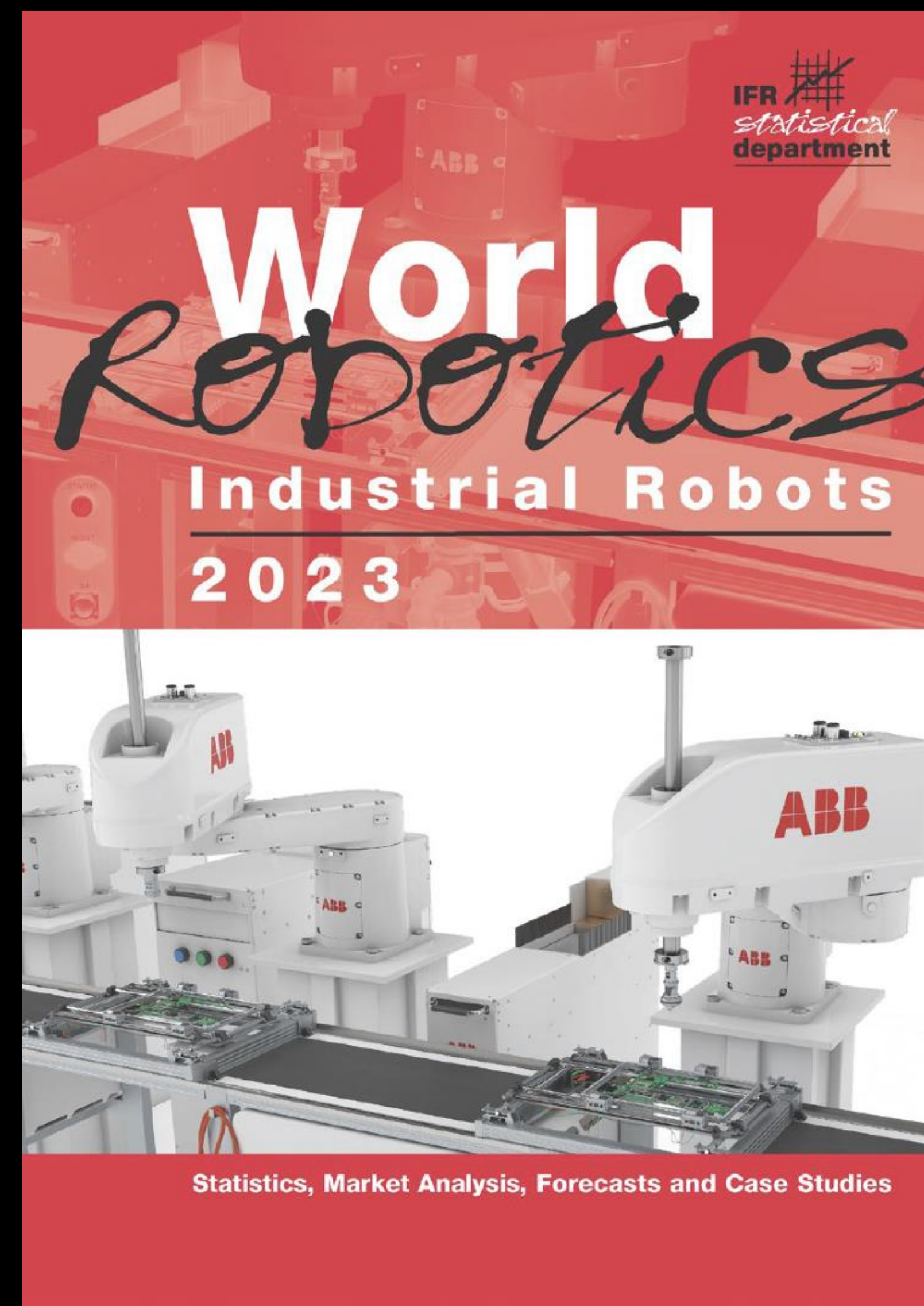


# Industrial Robotics Evolution



# Industrial Robots

- ✓ *3.9 million of robots @ work worldwide (+12%), CAGR 2017–2022 +13%*
- ✓ *553.000 new installation in 2022 (+5%), CAGR 2017–2022 +7%*
- ✓ *Largest markets: China, Japan, USA, Korea, Germany, Italy (91%)*



# Annual Installations

World record of 500,000 units exceeded

## Annual installations of industrial robots - World

1,000 units



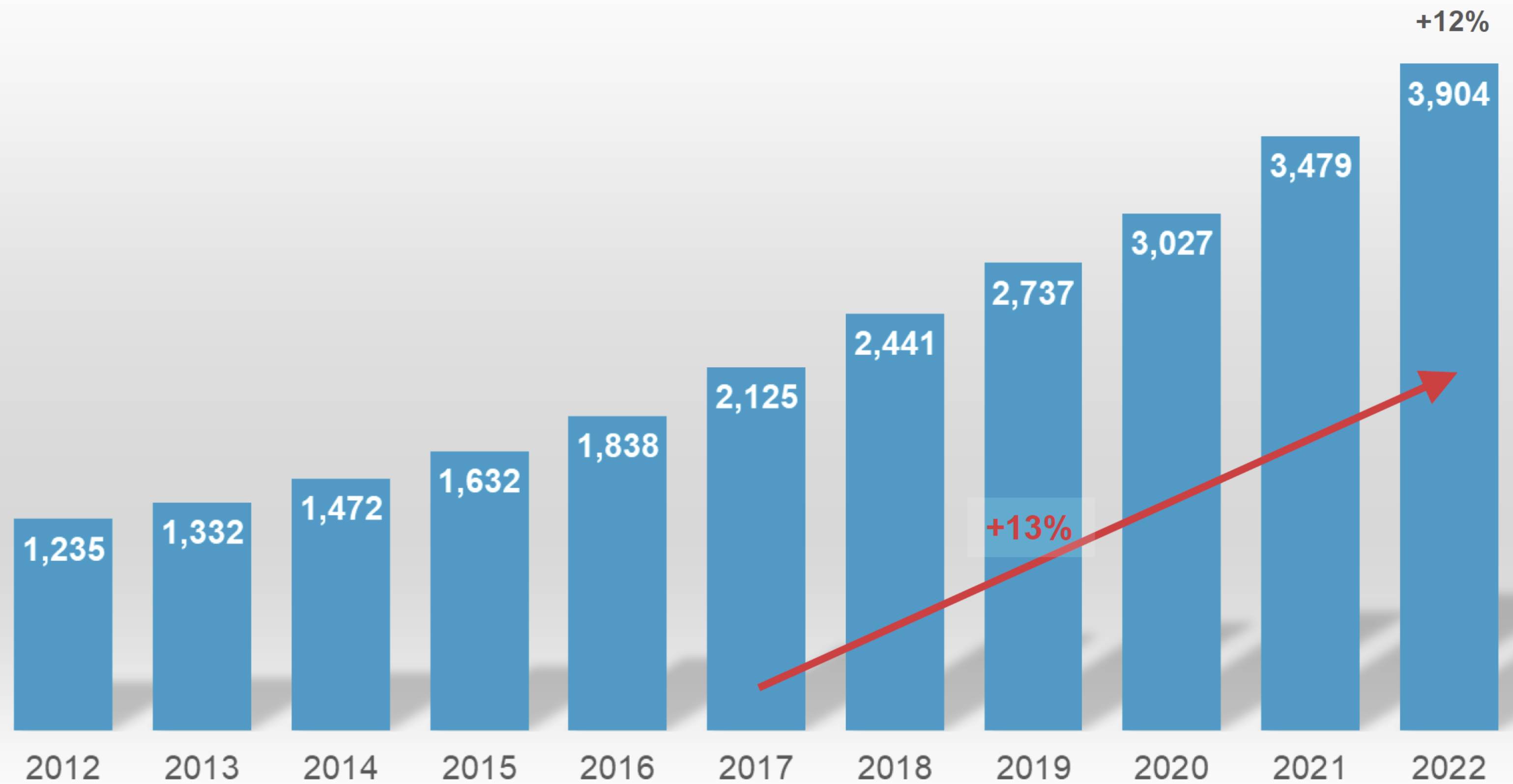
Source: World Robotics 2023

# Operational Stock

Almost 4 million industrial robots operating around the world

## Operational stock of industrial robots - World

1,000 units

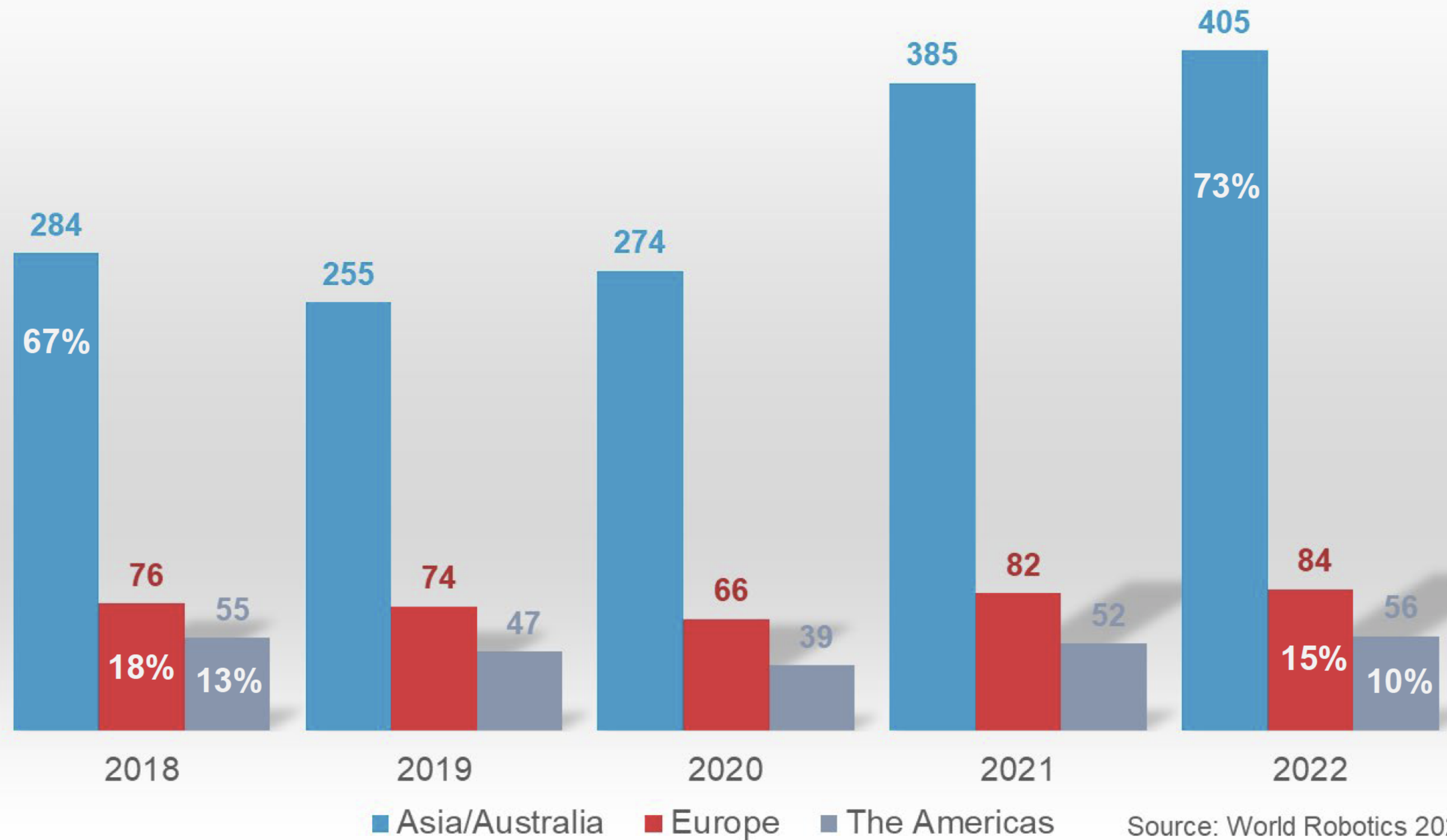


Source: World Robotics 2023

# Geographical Regions

Growth in all regions

Annual installations of industrial robots  
('000 of units)

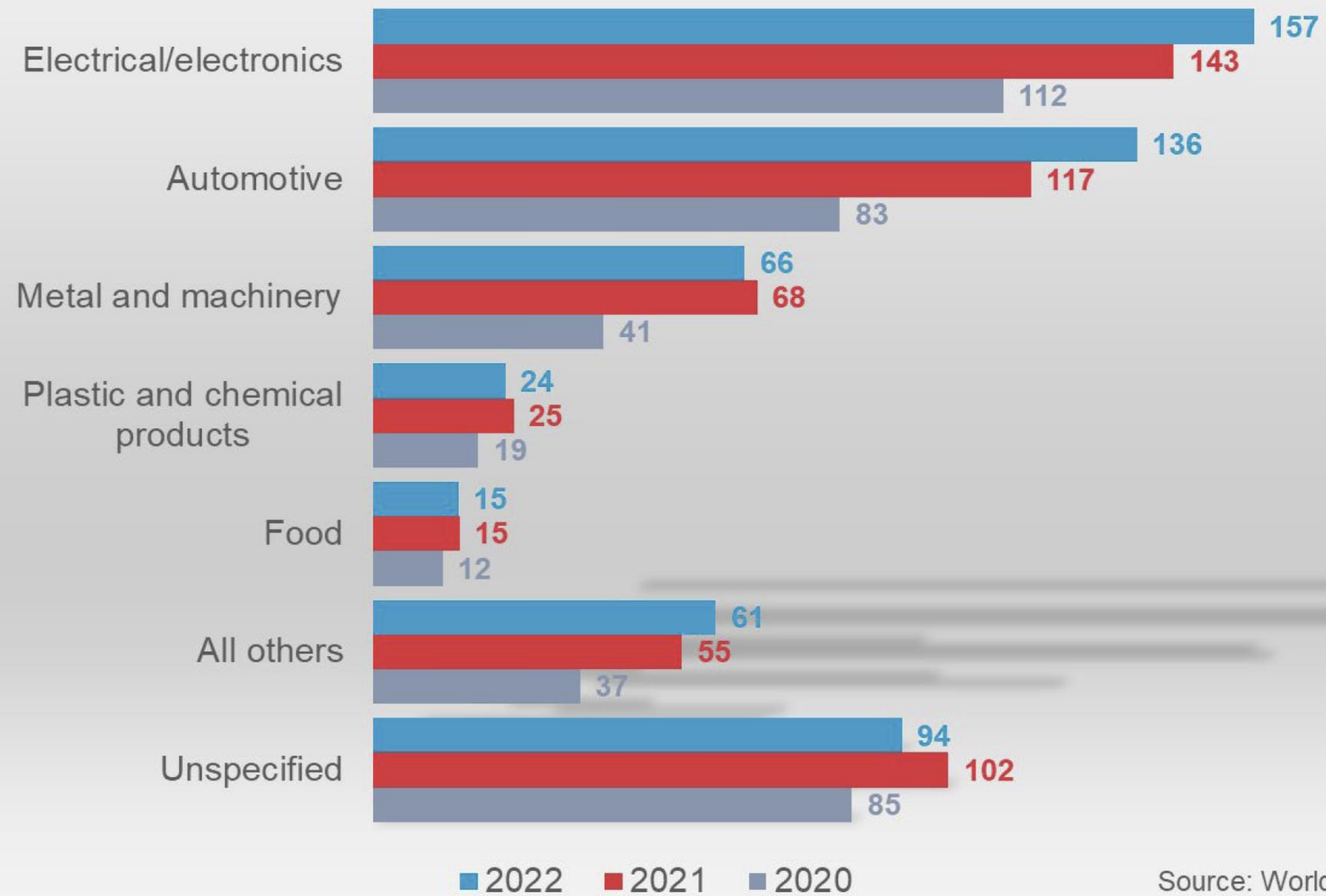


# Customer Industries

Electronics is major customer – challenges for general industry

## Annual installations of industrial robots by customer industry - World

1,000 units



Source: World Robotics 2023

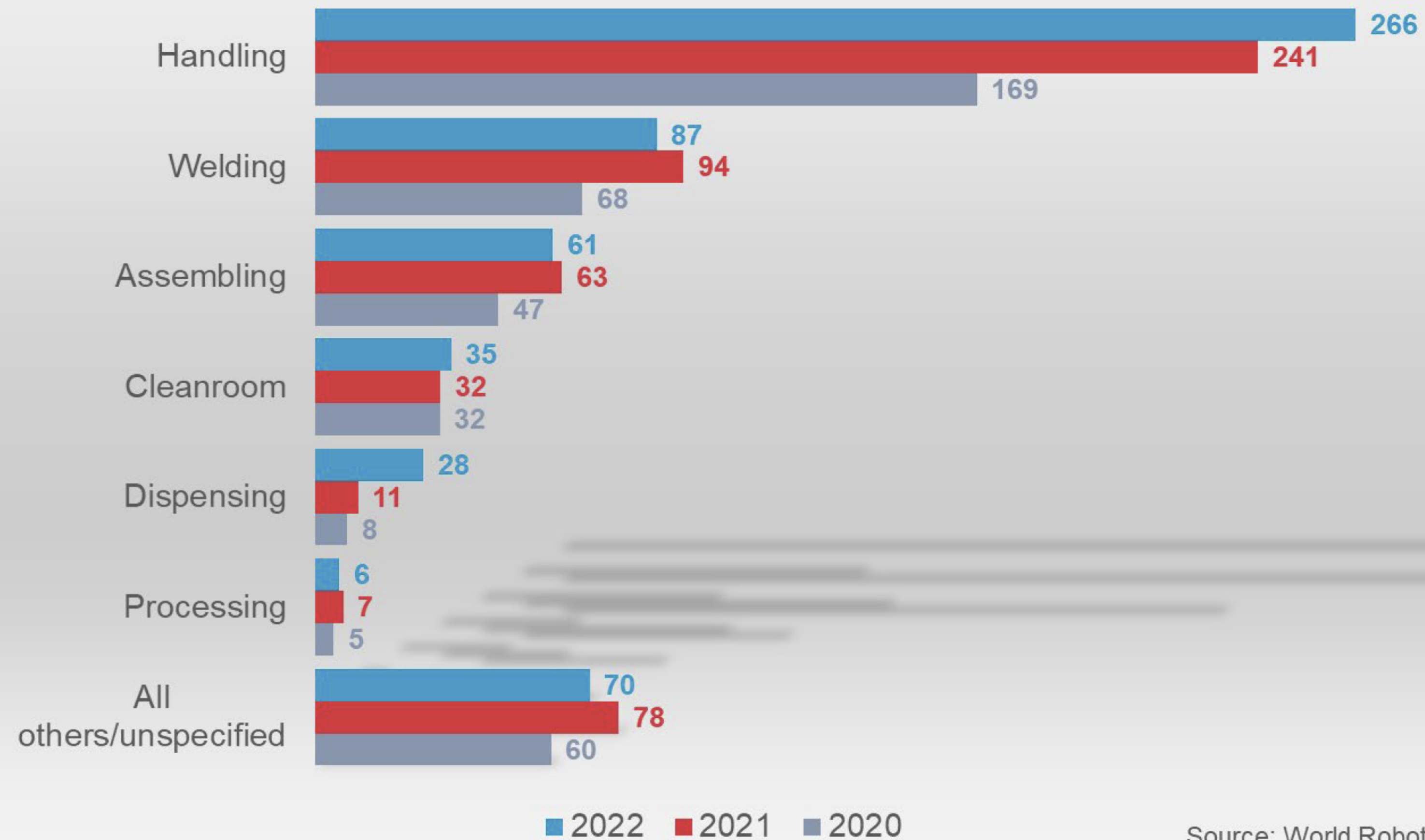


# Applications

Handling is most important application with 48% share

## Annual installations of industrial robots by application - World

1,000 units



Source: World Robotics 2023

# Forecast

Approaching the 600,000-unit mark in 2023

Annual installations of industrial robots 2017-2022 and 2023\*-2026\*



\*forecast

Source: World Robotics 2023

# Short-Term Market Determinants

*Supply chain constraints are easing*

*Inflation remains high*

*Slowdown of global economic growth*

- ✓ *No direct correlation to robot installations*
- ✓ *Development in China has strong impact on overall performance*

*Orders: backlog from 2022 and declining intake in 2023*

- ✓ *Orders from 2022 shipped in 2023*
- ✓ *Base effect: strong order intake in 2022*



# Technological Trends

## Cloud computing and 5G mobile networks

- ✓ new business models
- ✓ optimized performance
- ✓ fully digitalized production

## Machine vision

- ✓ simplifies programming
- ✓ detection of shapes and guide grippers in complex environments

## Artificial Intelligence coming to market

- ✓ smarter, faster, more efficient and more accessible automation
- ✓ enhancing maintenance
- ✓ faster programming, learning by experience
- ✓ supporting sustainability



# Market Trends

*Labor scarcity in many developed economies is driving the demand for automation*

*Reconsideration of supply chains and closeness to customers*

✓ *Re-and nearshoring of production*

*Small and medium sized enterprises (SMEs) need easy access to automation*

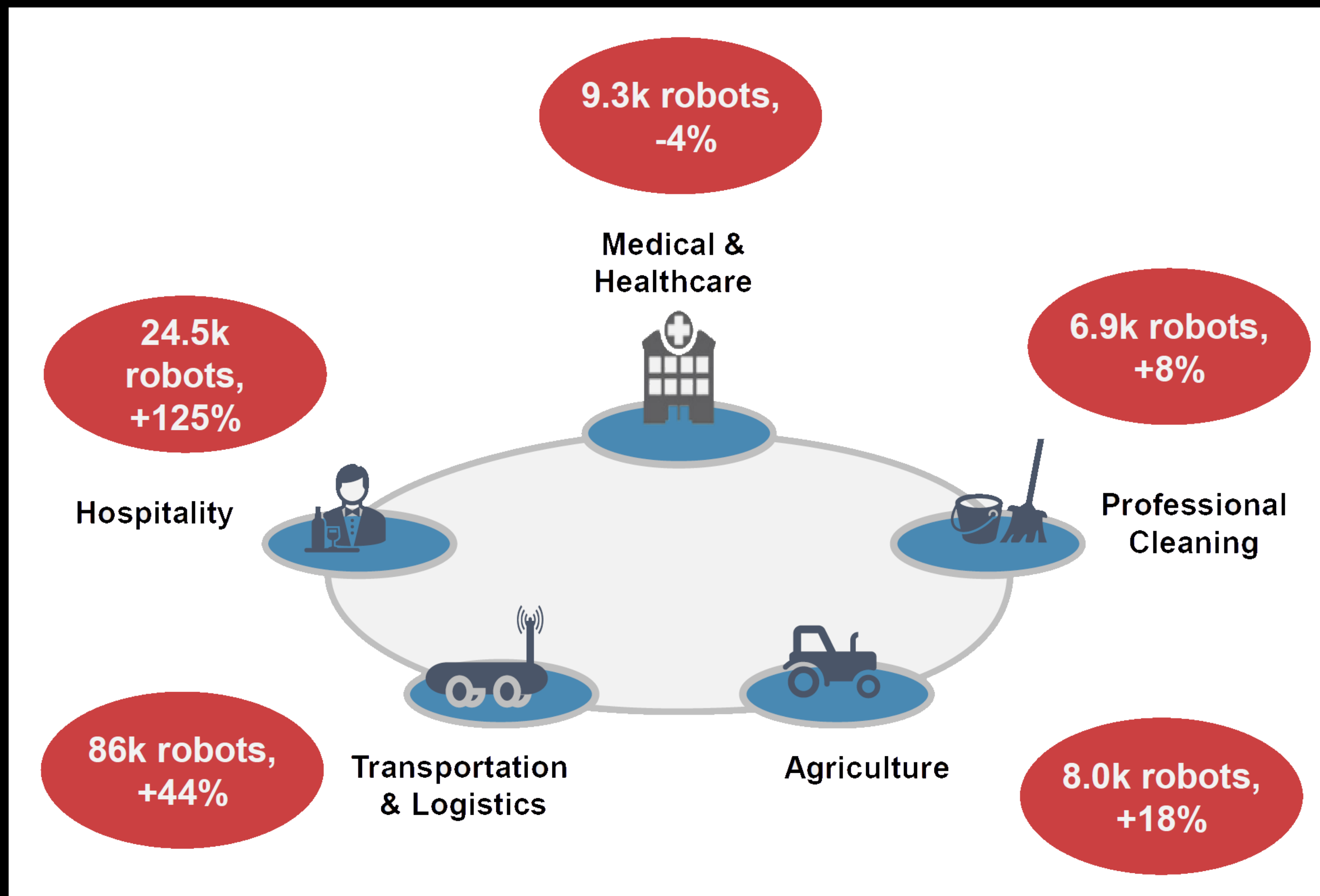
✓ *“Democratizing” robotics*

✓ *Lowering the hurdles for robotization: IFR’s Go4*

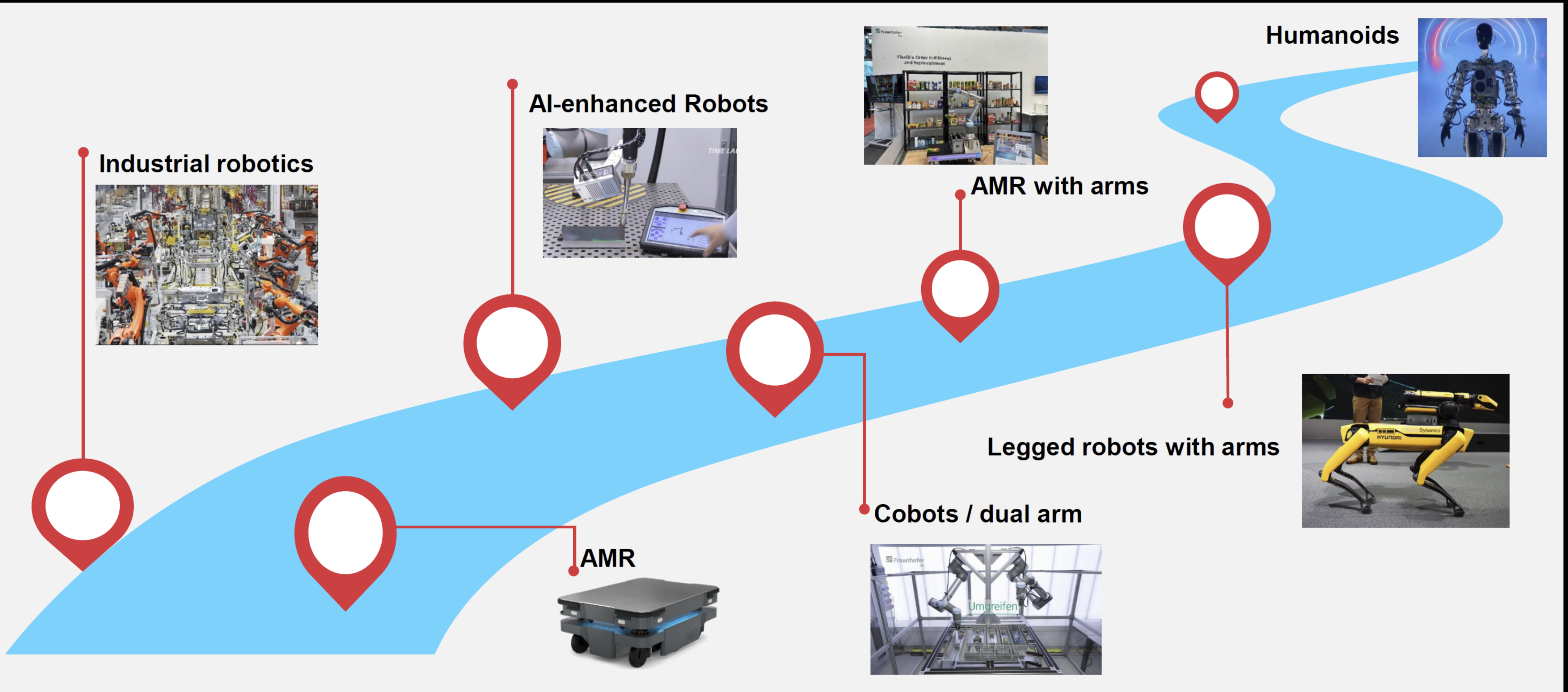
*Robotics campaign <https://go4robotics.com/>*



# Top 5 Application Areas of Professional Service Robots



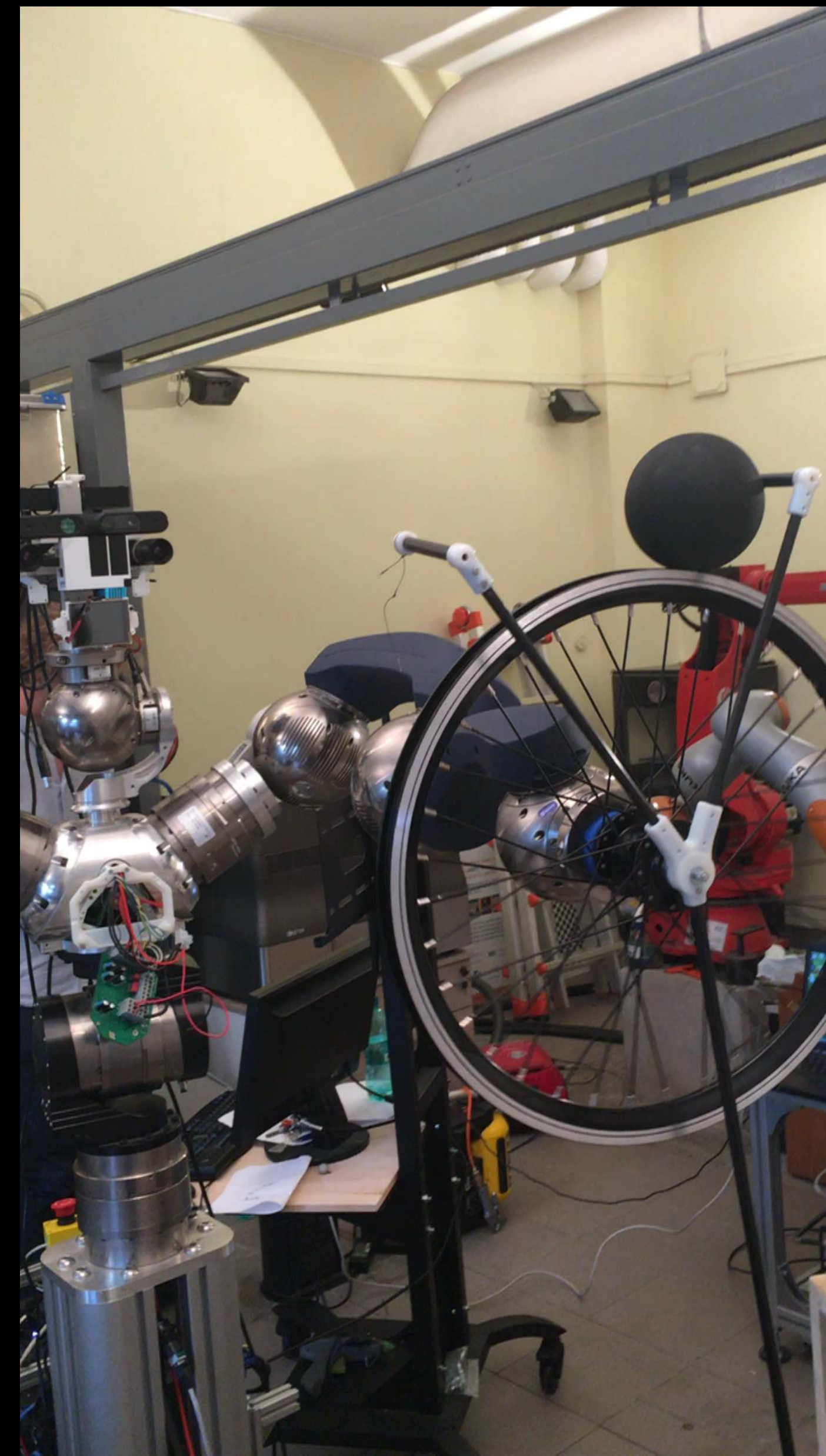
# Long-term Research Trends



# Humanoid Research @ PRISMA Lab

## *RoDyMan project*

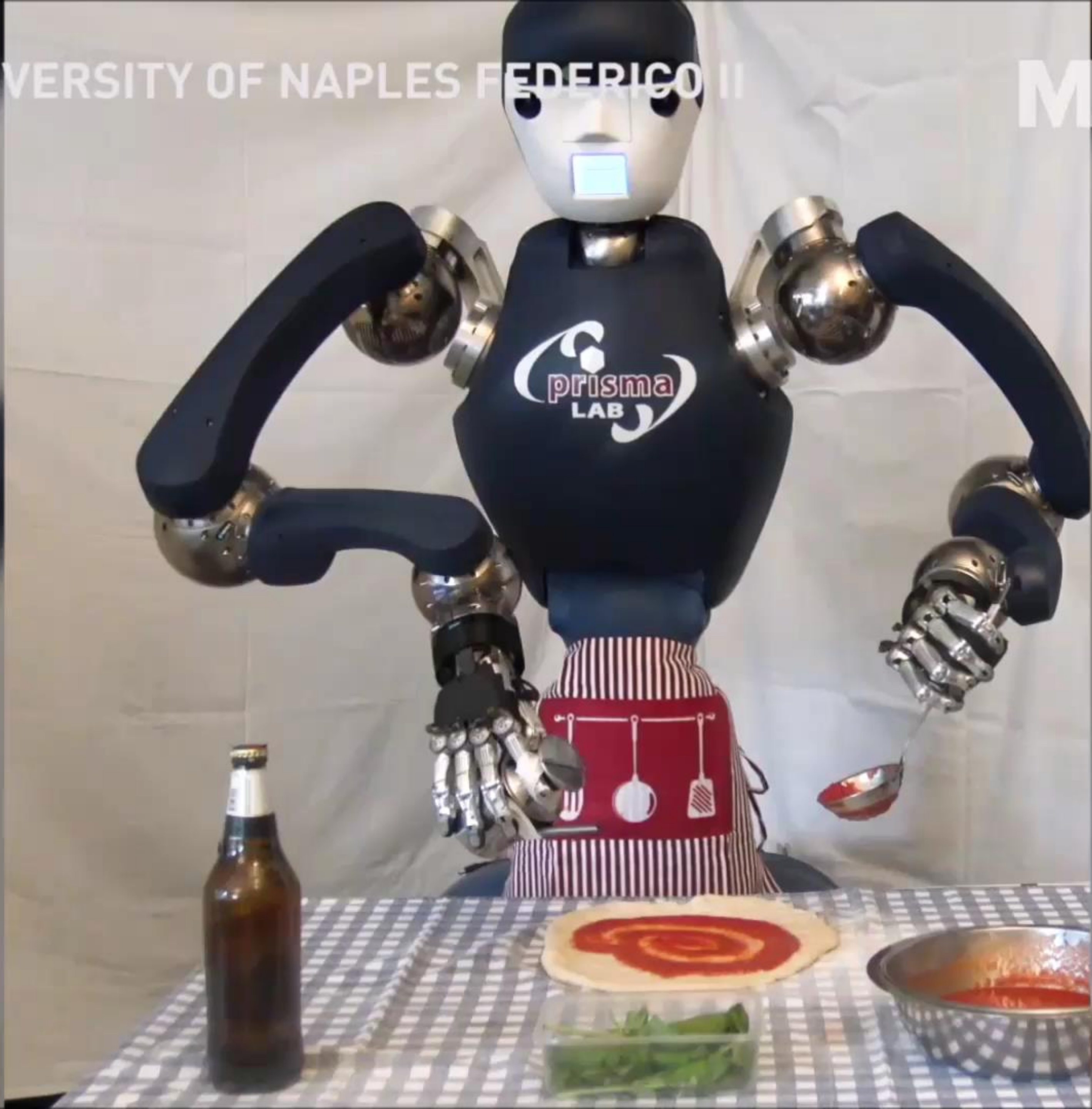
- ✓ *Dynamic nonprehensile manipulation is tested on an advanced demonstrator, i.e. **pizza making process**, where the application scenario is conceived to emulate the human ability to carry out a challenging robotic task*
- ✓ *Development of a service robot able to manipulate elastic and soft objects, as well as to manipulate both rigid and non-rigid objects in a nonprehensile way*





PRISMA LAB/UNIVERSITY OF NAPLES FEDERICO II

Mashable



**RODYMAN**

erc 7  

### ROBOTIC DYNAMIC MANIPULATION

Funding scheme: Advanced Grant  
Grant agreement no: 320992  
Starting date: June 2013  
Duration: 24 months  
Principal Investigator: Prof. Bruno Siciliano  
Host Institution: Consorzio G.R.E.A.T.E.


Have you ever thought about the complexity of making pizzas? Stretching the dough, tossing, seasoning, baking with dynamic turning. It is a real art. A robot - named **RODYMAN** - has the required dexterity to reproduce this gastronomic choreography. With unprecedented manipulation skills and an enhanced ability to work in human environments, **RODYMAN**'s future looks bright. From assisting elderly people to repairing a human limb: the potential applications of **RODYMAN** are numerous and can greatly improve our daily lives.

The goal of the **RODYMAN** project is the derivation of a unified framework for dynamic manipulation where the mobile nature of the robotic system and the manipulation of non-prehensile non-rigid or deformable objects will explicitly be taken into account. Novel techniques for 3D object perception, dynamic manipulation control and reactive planning will be proposed. An innovative mobile platform with a torso, two lightweight arms with multi-fingered hands, and a sensorized head has been developed for effective execution of complex manipulation tasks, also in the presence of humans.



[www.rodyman.eu](http://www.rodyman.eu)

**RODYMAN**



**Maker Faire**

**RODYMAN**  
MANIPOLAZIONE  
ROBOTICA NONPREHENSIBILE  
DI OGGETTI DEFORMABILI

SAPIENZA  
UNIVERSITÀ DI ROMA



DIAG  
Dipartimento di  
Ingegneria Informatica,  
Matematica e Gestionale  
Antonio Ruberti

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